

Qinghang Liu

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Education

Peking University

B.S. in Engineering and Scientific Computing
B.S. in Economics
• GPA: 3.76/4.0 (Top 20%)

Beijing, China

Sep, 2022 – Jul, 2026
Sep, 2023 – Jul, 2026

Research Experience

SwarmPRM: Probabilistic Roadmap Motion Planning for Large-Scale Swarm Robotic Systems

Dec 2023 – Feb 2024

- Reproduce sampling-based algorithm dRRT* for comparison test.

MPC-Based Microscopic Control for Swarm System

March 2024 – July 2024

- We propose an algorithm that can control thousands of robots to follow a time-varying formation in the shape of a Gaussian Mixture Model.
- The MPC-based algorithm can generate energy-saving and collision-free trajectories for robots in clustered environments.
- We have deployed the algorithm on real-world robot cars to show its robustness.

Reinforcement Learning-Driven Target Tracking and Hunting using Large-Scale Swarm Robots

August 2024 – Present

- We propose an RL algorithm that can generate collision-minimized PDF trajectories, which can be used to guide the swarm to move.

Publications

SwarmPRM: Probabilistic Roadmap Motion Planning for Large-Scale Swarm Robotic Systems

IROS 2024

Yunze Hu, Xuru Yang, Kangjie Zhou, **Qinghang Liu**, Kang Ding, Han Gao, Pingping Zhu, Chang Liu

Projects

A self-designed deep learning framework

- Developed a deep learning framework in reference to PyTorch.
- Reproduced basic operators (convolution layer, fully connected layer) using CUDA, and designed the Autograd mechanism using Python.
- The framework can recognize hand-written digits in MNIST with an accuracy rate of over 70%.
- Tools Used: CUDA, Python

Technologies

Languages: C++, Python, Matlab, CUDA